



## CP Triveneto 2024 - Delta Fun

2024-04-06 to 2024-09-15, no FAI sanctioning

### Delta Fun - Borso del Grappa

2024-08-31 Borso del Grappa

Race to Goal 66.3 km

Provisional

#	Id	Name	Nat	Glider	Sponsor	SS	ES	Time [h:m:s]	Speed [km/h]	Distance [km]	Dist. Points	Lead. Points	Time Points	Total		
1	8	Alvise Ghirardi	M	ITA	Icaro MastR			14:15:00	16:36:08	02:21:08	26.7	66.31	470.5	92.7	436.8	1000.0
2	9	Manuel Baldin	M	ITA	WillsWing U2			14:15:00	17:01:17	02:46:17	22.7	66.31	470.5	51.0	288.6	810.1
3	3	Federico Romani	M	ITA	Icaro MastR			14:15:00				59.64	446.8	68.9		515.7
4	1	Paolo Zurlo	M	ITA	Icaro Orbiter 2			14:15:00				38.73	336.9	27.6		364.5
5	5	Katia Bruni	F	ITA	Icaro MastR			14:15:00				38.61	336.1	28.0		364.1
DNF	2	Valentino Tonellotto	M	ITA	Icaro Laminar											0.0
ABS	6	Giovanni Cortesi	M	ITA	WillsWing Sport 3											0.0
ABS	4	Paolo Merisio	M	ITA	WillsWing U2											0.0
ABS	7	Mario Sanseverino	M	ITA	Icaro Alto	Sanseverino Costruzioni										0.0

### Task definition

No	Leg Dist.	Id	Radius	Open	Close	Coordinates	Altitude
1	0.0 km	D03	400 m	12:45	15:00	Lat: 45.83708 Lon: 11.74892	1087 m
2 SS	2.8 km	B06	7500 m	14:15	15:00	Lat: 45.85825 Lon: 11.87815	337 m
3	8.8 km	B06	1500 m	14:15	18:30	Lat: 45.85825 Lon: 11.87815	337 m
4	27.6 km	B21	9500 m	14:15	18:30	Lat: 45.70582 Lon: 11.56415	110 m
5	47.8 km	B19	7000 m	14:15	18:30	Lat: 45.8766 Lon: 11.9675	166 m
6	60.7 km	D02	6000 m	14:15	18:30	Lat: 45.79373 Lon: 11.66282	873 m
7	64.0 km	A10	5000 m	14:15	18:30	Lat: 45.74133 Lon: 11.8066	95 m
8 ES	65.7 km	A02	1000 m	14:15	18:30	Lat: 45.80568 Lon: 11.78655	156 m
9	66.3 km	A02	400 m	14:15	18:30	Lat: 45.80568 Lon: 11.78655	156 m

### Task statistics

param	value
task_distance	66.314
ss_distance	62.901
launch_to_ess_distance	65.714
qnh_setting	1013.25
no_of_pilots_in_competition	9
max_time_en_route	00:00:00
max_time_en_route_tp	0
no_of_pilots_present	6
no_of_pilots_flying	5
no_of_pilots_lo	3
no_of_pilots_landed_before_stop	0
sum_dist_over_min	244.601
sum_real_dist_over_min	244.601
sum_flown_distances	269.601
best_dist	66.314
best_real_dist	66.314
best_time	2.3522
last_finisher_start_time	2024-08-31T14:15:00+02:00
last_start_time	2024-08-31T14:15:00+02:00
first_start_time	2024-08-31T14:15:18+02:00
first_finish_time	2024-08-31T16:36:08+02:00
last_ss_finish_time	2024-08-31T17:01:17+02:00
last_landed_before_ess_finish_time	2024-08-31T16:44:42+02:00
no_of_pilots_reaching_es	2
no_of_pilots_reaching_goal	2
max_time_to_get_time_points	3.8859
goalratio	0.4
arrival_weight	0
departure_weight	0
leading_weight	0.0927
time_weight	0.4368
distance_weight	0.4705
smallest_leading_coefficient	1.796
available_points_distance	470.5
available_points_time	436.8
available_points_departure	0
available_points_leading	92.7
available_points_arrival	0
time_validity	1
launch_validity	1
distance_validity	1
stop_validity	1
day_quality	1
ftv_day_validity	1
time_points_stop_correction	0

### Scoring formula settings

param	value
id	GAP2023
min_dist	5
nom_dist	25
nom_time	0.833333333333333333333333333333
nom_launch	0.8
nom_goal	0.3
day_quality_override	0
bonus_gr	5
jump_the_gun_factor	2
jump_the_gun_max	300

<b>param</b>	<b>value</b>
normalize_1000_before_day_quality	0
time_points_if_not_in_goal	0.8
use_1000_points_for_max_day_quality	0
use_arrival_position_points	0
use_arrival_time_points	0
use_departure_points	0
use_difficulty_for_distance_points	1
use_distance_points	1
use_distance_squared_for_LC	1
use_leading_points	1
use_semi_circle_control_zone_for_goal_line	1
use_time_points	1
scoring_altitude	GPS
final_glide_decelerator	none
no_final_glide_decelerator_reason	
min_time_span_for_valid_task	25
score_back_time	15
use_proportional_leading_weight_if_nobody_in_goal	0
leading_weight_factor	1
turnpoint_radius_tolerance	0.002
turnpoint_radius_minimum_absolute_tolerance	5
number_of_decimals_task_results	1
number_of_decimals_competition_results	0
redistribute_removed_time_points_as_distance_points	1
use_best_score_for_ftv_validity	1
use_constant_leading_weight	0
use_pwca2019_for_lc	0
use_flat_decline_of_timepoints	1
use_leading_time_ratio	0
optimize_ss_alone	0